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#### I. Introduction

This report discusses the ramifications of a simple observation of projectile free flight behavior. The observation is that for certain projectile types, when velocity is plotted against range, the data lie in a straight line, as long as the velocity is above Mach 2.5. Examples of this behavior are shown in Figures 1A and 1B. These figures are derived from calculated trajectories based on the standard firing tables data for these rounds. Figure 1A shows three large caliber fin-stabilized projectiles. Figure 1B shows four other projectiles including a spikenosed high explosive projectile (M831) and a .50 caliber sabot-launched armor liercing projectile (SLAP). The diversity of these projectiles seems to imply that the observation holds true for a variety of projectile types.

#### ll. Implications

There are several implications of this behavior. The first is that the derivative of velocity with respect to range is constant (the slope of the line). If range is expressed in units of the projectile reference length,  $\ell$ , then this derivative is the term dV/ds in the drag equation<sup>1</sup>:

$$C_D = -(dV/ds)(1/V)(2m/\rho S\ell)$$
 (1)

For any given shot of a direct-fire weapon, the only variable term in this equation is the velocity, V. Rewriting V as Ma (Mach number times sound speed) and combining all of the constants into one term, K:

$$K = -(dV/ds)(1/a)(2m/\rho S\ell)$$
 (2)

Equation (1) becomes:

$$C_{D} = K/M \tag{3}$$

This is an extremely simple form for the drag equation, with several important implications. One implication is that one test shot can be fired, the factor K can be determined, and drag as a function of Mach number is then known for that projectile type for all Mach numbers above 2.5. Unfortunately, the effects of projectile yaw make things a little more complicated. Drag is assumed to depend on two independent variables: the Mach number, M, and  $\delta^2$ , the square of the yaw. The drag equation is thus written as:

$$C_D(M, \delta^2) = C_{D0}(M) + C_{D\delta}^2 \delta^2$$
 (4)

where  $C_{D\theta}$  is the 'zero-yaw drag coefficient' and  $C_{D\theta}$  is the 'yaw-drag coefficient'.

Another important result is obtained when Equation (3) for  $C_D$  is entered in the drag force equation<sup>1</sup>:

$$D = \frac{1}{2}\rho V^2 SC_D$$

$$D = \frac{1}{2}\rho (Ma)^2 S (K/M)$$

$$D = \frac{1}{2}\rho a^2 S K M$$
(5)

Again, for a given shot, the only variable is the Mach number. Thus, the drag force is directly proportional to the projectile velocity.

#### III. Applications

There are several applications with varying levels of usefulness. The first is an alternative method of reducing free-flight spark range data for drag by using the slope of a velocity vs. range plot. However, because the technique is limited to specific projectile types and velocities, the method has limited usefulness when compared with the present data reduction techniques.

A more useful application would be to use the technique to obtain a value of  $C_{\rm D}$  for velocity/range data that consists of sparse measurements (e.g. skyscreens). Since the velocity degradation is a straight line, it is possible to obtain a value of  $C_{\rm D}$  if velocity is only measured at two points (preferably far apart). The technique can also be used to extract  $C_{\rm D}$  from doppler radar data. A FORTRAN program that calculates  $C_{\rm D}$  from an arbitrary set of velocity/range data points is included as Appendix A.

Other applications are based on the fact that what one obtains from the velocity/range data is actually the variation of  $C_D$  with Mach number, not just a value of  $C_D$  at a particular Mach number. Thus, a  $C_D$  curve can be determined from one test round.

This leads to perhaps the most useful application - the more accurate determination of the yaw-drag coefficient and  $C_{\rm D0}$  by the elimination of the Mach number variations. For a single shot, the drag will depend on both the zero-yaw drag and the yaw-drag components. The yaw-drag is dependent on the average yaw value for that shot. If the firing is done over a long range, the yaw should damp out and one should get the value of  $C_{\rm D0}$ . However, for shorter distances such as the free flight spark ranges, the yaw-drag will have a significant effect.

One common technique for determining  $C_{D0}$  and  $C_{D\delta}$  is to fire groups of shots at different Mach levels (e.g. five shots at M=3, five shots at M=4, etc.). For each of these groups, the measured value of  $C_D$  for each shot is plotted against the average square yaw for that shot. A straight line is then fitted to the data, with the slope of the line being  $C_{D\delta}$  and the intercept being  $C_{D0}$  at that Mach number (see Equation 4). However, if there is some Mach number variation within the group, there is no simple way to eliminate the drag variation with Mach number from the data.

(One method for compensating for Mach number variation, the "Q-function", is described in Reference 2. In order to apply this technique, however, at least two low-yaw data points are required at significantly different Mach numbers. These points are then used to determine the  $C_{\rm D0}$  variation with Mach number .)

For the case where the drag function has the form K/M, there is another technique. If one assumes that the yaw-drag coefficient,  $C_{D\delta}^2$  is a function of yaw only (independent of Mach number), and that  $C_{D\delta}$  has the form K/M, then it can be shown that for a series of range firings one can plot  $(M/M_{REF})C_D$  vs.  $(M/M_{REF})\delta^2$ , and the intercept of a straight line fitted to the data will be  $C_{D\delta}$  at  $M_{REF}$ , and the slope will be  $C_{D\delta}^2$ . Alternatively, if M=1 is used for  $M_{REF}$ , the intercept will be the constant, K. A FORTRAN program that does this calculation using a set of  $(M, C_D, \delta^2)$  data points is included as Appendix B.

Since Mach number variation is effectively removed from the data, the data points do not have to be at the same Mach number in order to do the fit. Also, since the only fit being done is a straight line, the drag coefficient can be completely defined (both  $C_{\rm D0}$  as a function of Mach number and  $C_{\rm D0}$ ) with just two well-determined data points, providing they are at different yaw levels.

#### IV. Examples

An example of each of the applications listed previously will be given. The examples use the data from BRL Transonic Range firings of untraced, ambient temperature, DM13 projectiles. The DM13 is a fin-stabilized KE penetrator with a tungsten core, fired from a 120 mm smoothbore gun tube.

### 1. Determination of CD From Velocity vs. Range Data

Figure 2 is a plot of velocity vs. range for Transonic Range round number 17682. The range measures position and time, so the velocity was calculated between each two successive timing stations by dividing the difference in distance by the difference in time between the two stations. The resulting average velocity was said to have occurred midway between the two stations because of the assumed linear behavior of velocity with range. Table 1A lists the position, time, and velocity data. A least-squares linear fit was performed on the velocity-range data. The slope of this fit, together with the measured physical properties and meteorological data at the time of the test (Table 13) were used to determine K, using Equation 2. The value of K for this shot was found to be 1.402.

The values of  $C_D$  and M from the standard range reduction for this round number are 0.2904 and 4.823, respectively. At this Mach number, the calculated  $C_D$  using Equation 3 is:

$$C_D = K/M = 1.402 / 4.823 = 0.2907$$

### 2. Extrapolation of CD to Other Mach Numbers

The previous example showed how to determine K and, subsequently,  $C_D$  from velocity vs. range data. If one were to start with a value of  $C_D$  from a standard range reduction, K can be calculated by:

$$K = C_{p}M \tag{6}$$

For round 17682, this yields:

$$K = 0.2904 (4.823) = 1.401$$

Table 2 contains a round-by-round listing of measured drag data from the BRL Transonic Range. Figure 3 is a plot of  $C_D$  vs. M including the measured values from Table 2, as well as the curve  $C_D=1.401/M$ . The measured value for round 17682 is the solid symbol. The extrapolated drag curve from this one data point is in excellent agreement with the other data. Note that round 17682 had very low yaw, so the curve should be a good approximation of  $C_{D0}$ . For this reason, most of the other data lie somewhat above the curve.

#### 3. Calculation of the Drag Force

Equation 5 can be used to calculate the actual drag force experienced by a projectile. Using values from the previous examples:

$$D = K[\frac{1}{2}\rho a^2S]M = 1.4[\frac{1}{2}(1.23)(339.6)^2(0.001137)]M = 112.9 M$$

At the launch Mach number of 4.86, the drag force is:

$$D = (112.9)(4.86) = 548.7 N (123.4 lbf)$$

## 4. Determination of C<sub>D0</sub> and C<sub>D6</sub>2

Figure 4 is a plot of  $C_D$  vs.  $\delta^2$  for all of the measured data. Most of the scatter in the data is due to Mach number variations (in this case, from M=3.27 to M=4.83). Figure 5 shows  $(M/M_{REF})C_D$  plotted against  $(M/M_{REF})\delta^3$ , using  $M_{REF}=4.7$ . In this case, the scatter has been greatly reduced because the Mach number variation has been eliminated. A linear least-squares fit of the data gives the slope, or  $C_{D\delta}$ s, as 13.212, and the intercept, or  $C_{D\delta}$  at M=4.7, as 0.298. Using Equation 6, the constant K can be calculated as being 1.401. Thus, the drag equation is:

$$C_{\rm p}(M, \delta^2) = 1.401/M + 13.212 \delta^2$$

The advantage of this method, however, is that these coefficients can be determined from very limited data. The previous calculation can be repeated using only the three dark data points in Figures 4 and 5. These points are from rounds 17683, 26417, and 17691, which had the highest Mach number, largest yaw, and lowest Mach number, respectively. In this case, the calculated values are:  $C_{D\delta}^2 = 9.976$ ,  $C_{D0} = 0.297$ , and K = 1.397. The drag equation is then:

$$C_D(M, \delta^2) = 1.397/M + 9.976 \delta^2$$

which is a good approximation, considering only three data points were used.

#### V. Restrictions

So far, it has not been possible to completely define restrictions on the use of these equations. The restrictions that have been identified are: the projectile velocity must be above Mach 2.5 and the ambient conditions cannot change significantly over the flight path. These restrictions are met by most large- and medium-caliber direct-fire weapons.

One problem with defining restrictions is that it has been difficult to find projectiles that do not obey the equations. In fact, the only projectile found so far that does not exhibit this behavior is the 25 mm M910 training round, which simulates some of the characteristics of the M791.

#### VI. Summary

A technique has been described that can be used to completely determine the drag coefficient using very limited drag data. The technique assumes  $C_{\rm D0}$  has the form K/M. The overall findings of this report can be summarized as follows:

- 1. Almost all ammunition examined so far slows down at a rate such that a plot of velocity vs. range will yield a straight line, as long as the velocity is above Mach 2.5.
- 2. This type of behavior dictates that C<sub>D</sub> has the form K/M.
- 3. The slope of the straight line in a plot of velocity vs. range can be used to determine the value K and, consequently, C<sub>D</sub> as a function of Mach number.
- 4. If  $C_{D0}$  has the form K/M and  $C_{D}$  has been determined at (at least) two different yaw levels,  $C_{D}$  as a function of both M and  $\delta^{2}$  can be completely defined.
- 5. If  $C_D$  has the form K/M, the drag force is directly proportional to the projectile velocity.

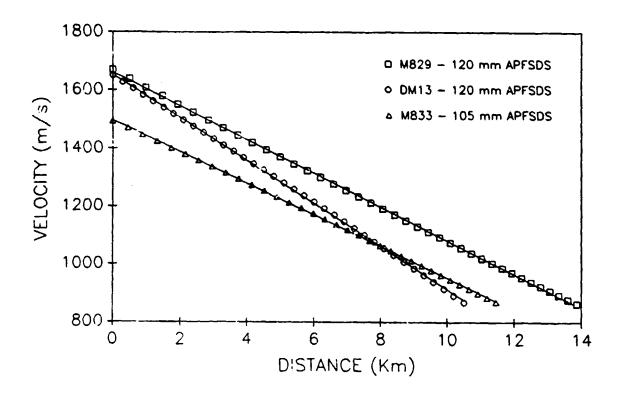


Figure 1A. Velocity vs. Range, Large Caliber Fin-Stabilized Projectiles.

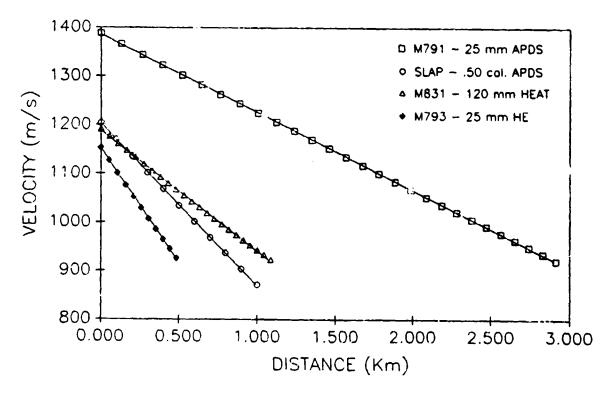


Figure 1B. Velocity vs. Range, Miscellaneous Projectiles.

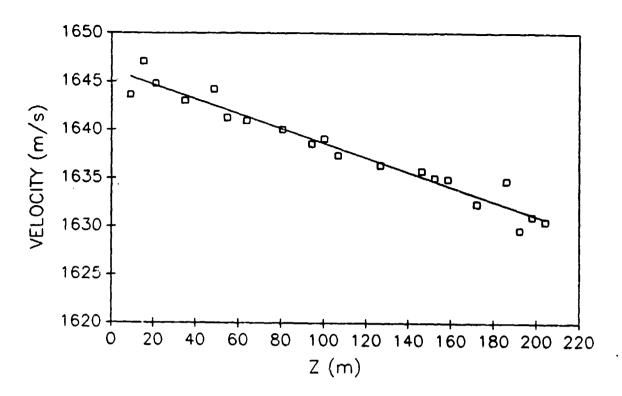


Figure 2. Velocity vs. Range, Transonic Range Round 17682.

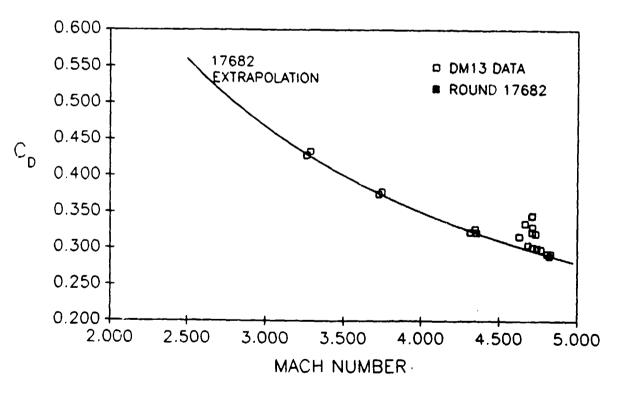


Figure 3. Coefficient of Drag vs. Mach Number.

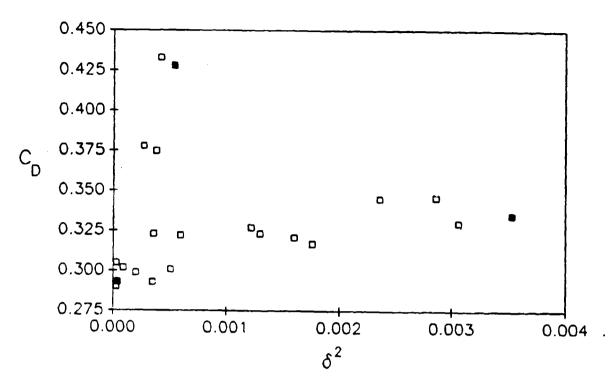


Figure 4. Coefficient of Drag vs. Delta Squared, Raw Data.

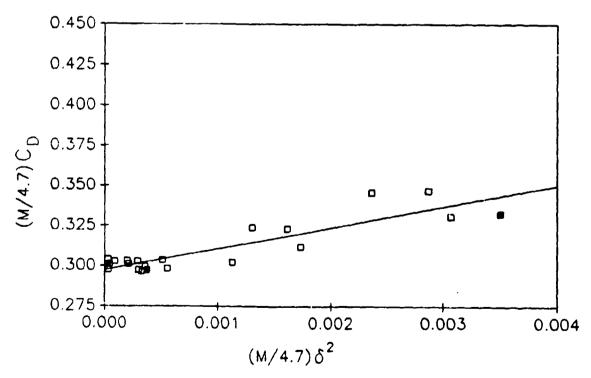


Figure 5. Coefficient of Drag vs. Delta Squared, Corrected for Mach Number

Table 1A. Time, Position, and Velocity for Transonic Range Round 17682.

Measured		Calculated		
Time (millisec.)	Range (meters)	Range (meters)	Velocity (meters/sec.)	
292.6346	5.772	8.937	1643.617	
296.4863 300.1130	12.103 18.076	15.089	1647.069	
303.7899	24.124	21.100 34.919	1644.795 1643.029	
316.9303	45.714	48.698	1644.226	
320.5601 324.3706	51.682 57.936	54.809	1641.255	
331.6055	69.808	63.872 80.653	1640.940 1640.045	
344.8312 348.2219	91.499 97.056	94.277	1638.571	
352.1388	103.475	100.265 106.816	1639.088 1637.364	
356.2205	110.158	126.686	1636.366	
376.4219 380.1552	143.215 149.322	146.268	1635.766	
383.8402	155.347	152.334 158.588	1635.065 1634.923	
387.8047	161.828	172.141	1632.375	
400.4403 404.7283	182.454 189.464	185.959	1634.753	
408.0961	194.953	192.208 198.013	1629.679 1631.065	
411.8493 415.5895	201.074 207.173	204.124	1630.585	

Table 1B. Projectile Physical Properties and Ambient Conditions.

$\ell = .03805 \text{ m}$	reference length, projectile body diameter
$S = 0.001137 \text{ m}^2$	reference area
m = 4.4282 Kg	projectile mass
$\rho = 1.234 \text{ Kg/m}^8$	air density
a = 339.63  m/s	sound speed

Table 2. Transonic Range Data for DM13 Projectiles.

Round No.	Mach No.	C <sub>D</sub>	δ3	
17683	4.832	0.293	0.00004	
17682	4.823	0.290	0.00003	
17681	4.807	0.293	0.00035	
17692	4.767	0.299	0.00020	
26443	4.743	0.301	0.00051	
26390	4.735	0.321	0.00160	
26442	4.715	0.302	0.00009	
26391	4.714	0.330	0.00306	
26289	4.714	0.346	0.00286	
26288	4.713	0.323	0.00130	
26417	4.711	0.345	0.00236	
26444	4.687	0.305	0.00003	
30691	4.666	0.335	0.00353	
30687	4.630	0.317	0.00176	
17685	4.357	0.322	0.00060	
17686	4.347	0.327	0.00122	
17687	4.317	0.323	0.00036	
17688	3.748	0.378	0.00027	
17689	3.728	0.375	0.00038	
17690	3.288	0.433	0.00042	
17691	3.265	0.428	0.00054	

#### References

- 1.) Murphy, C.H., "Free Flight Motion of Symmetric Missiles," US Army Ballistic Research Laboratory, Aberdeen Proving Ground, Maryland, BRL Report No. 1216, July 1963. (AD 442757)
- 2) Thomas, R.N., "Some Comments on the Form of the Drag Coefficient at Supersonic Velocity," BRL Report No. 542, April 1945. (AD 494220)

## List of Symbols

Symbo	1	Description	Equation
	-	speed of sound	
$C^{D}$	•	coefficient of drag	$-(dV/ds)(1/V)(2m/\rho S\ell)$
c ,	•	zero-yaw drag coefficient	
C <sub>D</sub> 62	-	quadratic yaw drag coefficient	
D	-	drag force	iρV <sup>2</sup> SC <sub>D</sub> C <sub>D</sub> M
K		drag constant	C <sub>D</sub> M
Ł	•	projectile reference length, usually body diameter	
m	-	projectile mass	
M	•	Mach number	
\$	•	dimensionless arc length along the trajectory	
S	•	reference area	$\pi t^2/4$
v	•	projectile velocity	
δ2	-	effective squared yaw	
ρ	•	air density	

## Appendix A: FORTRAN Code that Calculates C<sub>D</sub> from Position and Velocity Data.

```
C
C
    CALC_CD.FOR
    THIS PROGRAM CALCULATES CD FROM Z-V DATA
    I MAXIMUM NUMBER OF POINTS
    PARAMETER (MAX = 100)
    CHARACTER+50 FHIN, FHOUT, STRING, FHOUT2
    CHARACTER RND*20
    DIMENSION Z(MAX), V(MAX), C(2)
100 FORMAT(A)
C
C
    GET ROUND DESIGNATION. INPUT DATA MUST BE IN A FILE CALLED
C
    "ROUND" 2V.DAT WERE "ROUND" CAN BE EITHER A ROUND TYPE OR
    A ROUND NUMBER
     ***********************************
    WRITE(6,*)
    WRITE(6,*)'ENTER ROUND DESIGNATION'
    READ(5,100)RND
     fwin = RND//' ZV.DAT'
     FNOUT = RND//'.CD'
     C
     READ 2-V PAIRS FROM FILE AND CALCULATE AVERAGE VELOCITY
     OPEN( UNIT=1, FILE=FNIN, STATUS='OLD', READONLY )
       DO 10 1=1, MAX
        READ(1,*,END=11)2(1),V(1)
         SUM = SUM + V(1)
       CONTINUE
 10
     CLOSE(1)
     N = 1 - 1
     AVG_V = SUM / FLOAT(N)
     ENTER PHYSICAL PROPERTIES AND ATMOSPHERIC DATA
     ***********************************
     WRITE(6,*)
     WRITE(6,*)'ENTER PROJECTILE DIAMETER, L (M)'
     READ(5, *)XL
     WRITE(6,*)
     WRITE(6,*)'ENTER PROJECTILE MASS, m (KG)'
     READ(5,*)XMASS
     WRITE(6,*)
```

```
WRITE(6,*)'ENTER AIR DENSITY, tho (KG/M*+3)'
    READ(5,*)RHO
    WRITE(6,*)
    WRITE(6,*)'ENTER VELOCITY OF SOUND, a (M/S)'
    READ(5, *)A
    UR1TE(6,*)
    AVG_M = AVG_V / A
    WRITE(6,*)'ENTER REFERENCE MACH NUMBER, M*'
    WRITE(6,*)' (AVERAGE MACH MUMBER 15 ',AVG_M,' )'
    READ(5,*)XMSTAR
    CALCULATE THE FACTOR K AND CD AT THE REFERENCE MACH NUMBER
    *****************************
    PI = 3.1415927
    $ = (P1/4.) * XL**2
                             ! REFERENCE AREA
    RDF = (RHO*S*XL) / (2.*XMASS) ! RELATIVE DEHSITY FACTOR
    CALL LSQ1( 2, V, N, C )
    DRAGDOWN = C(2)
    DVDS = C(2) * XL
    XK = -DVDS / (RDF*A)
    CDREF = XK / XMSTAR
    WRITE(6.4)
    WRITE(6,*)'CD(M) = K/M, K = ',XK
    WRITE(6,*)'CD(MREF) = ',CDREF
    WRITE(6,*)
    SAVE CO VS. M AS PLOTTABLE FILE
    ***********************************
    XMIN = 2.5
    XMAX = 5.0
    XSTEP = (XMAX-XMIN) / FLOAT(MAX)
    XM = XMIN - XSTEP
    OPEN(UNIT=2, FILE=FNOUT, STATUS='NEW')
       DO 20 J=1, MAX
        104 = 104 + XSTEP
        CD = XK / XM
        WRITE(2,*)XH,CD
       CONTINUE
20
    CLOSE(2)
    STOP
    END
```

```
C
C
      SUBROUTINE TO CALCULATE LINEAR LEAST SQUARES FIT
C
      SUBROUTINE LSQ1(X,Y,N,C)
      PARAMETER ( MAX=100 )
      IMPLICIT DOUBLE PRECISION (A-H, O-Z)
      REAL 4 X(MAX), Y(MAX), C(2), SUM, ERROR
      RN=FLOAT(N)
      SUNCE-0.0
      SUMY=0.0
      SURCY=0.0
      SUNX2=0.0
      DO 10 J=1,N
         DUBX = X(J)
                              I DOUBLE PRECISION X
         DUBY = Y(J)
         SURX = SURX + DUSX
          SUMY = SUMY + DUBY
          SUMXY = SUMXY + DUBX*DUBY
         SUMX2 = SUMX2 + DUBX**2
     CONTINUE
 10
      DUBC2 = (RH*SUMXY-SUMX*SUMY) / (RH*SUMX2-SUMX**2)
      DUBC1 = (SUMY/RN) - (DUBC2*SUMX/RN)
      C(2) = DU8C2
      C(1) = DUBC1
      RETURN
      END
```

-------

## Appendix B: FORTRAN Code that Calculates $C_{D0}$ and $C_{D\delta}^2$ from (M, $C_D$ , $\delta^2$ ) Data.

```
***********************************
C
C
     CD_DELSQ.FOR
     THIS PROGRAM CALCULATES COO AND CO-DELSO
     FROM RAW M, DELSO, CD DATA
     ***********************************
                                I MAXIMUM MUMBER OF POINTS
     PARAMETER(MAX = 100)
     CHARACTER FHIN*50
     DIMENSION XM(MAX), CD(MAX), DELSQ(MAX), NR(MAX)
     DIMENSION DELSGZ(MAX), CDZ(MAX), CDO(MAX), C(2)
 100 FORMAT(A)
     READ DATA FROM FILE AND CALCULATE AVERAGE MACH KUMBER
     ************************************
     WRITE(6,*)
     WRITE(6,*)'ENTER INPUT FILENAME'
     READ(5,100)FNIN
     SUM = 0.
     OPEN( UNIT=1, FILE=FNIN, STATUS='OLD' )
        DO 10 1=1, MAX
         READ(1,*,END=11)XM(1),CD(1),DELSQ(1)
         SUM = SUM + XM(1)
 10
        CONTINUE
 11
     CLOSE(1)
     N = 1 - 1
     AVG_M = $UM / FLGAT(N)
C
     *************************************
     GET REFERENCE MACH NUMBER AND SHIFT ALL DATA TO THAT MACH NO.
     *************************************
     WR1TE(6,*)
     WRITE(6,*)'ENTER REFERENCE MACH NUMBER'
     WRITE(6,*)' (AVERAGE MACH NUMBER IS ',AVG_M,')'
     READ(5,*)XMREF
     DO 20 1=1,M
        RATIO = XH(1) / XHREF
        CD2(1) = CD(1) * RATIO
        DELSQ2(1) = DELSQ(1) * RATIO
 20
    CONTINUE
```

```
***********************************
C
C
      CALCULATE COO AND CO-DELSO AT REFERENCE MACH NUMBER, WITH AND
C
      WITHOUT MACH NUMBER CORRECTION
£
      ************************************
      CALL LSQ1( DELSQ, CD, N, C, ERROR )
      WRITE(6,*)
      WRITE(6, *) WITHOUT MACH NUMBER CORRECTION'
      WRITE(6,*)'CD0 = ',C(1)
      WRITE(6,*)'CD DELSQ = ',C(2)
      WRITE(6,*)'ERROR = ',ERROR
      CALL LSQ1( DELSQ2, CD2, N, C, ERROR )
      WRITE(6.*)
      WRITE(6,*)'WITH MACH MUMBER CORRECTION'
      WRITE(6,*)'CD0 * ',C(1)
      WRITE(6,*)'CD DELSQ = ',C(2)
      WRITE(6,*)'ERROR = ',ERROR
      WRITE(6,*)
      CD_DELSQ = C(2)
      STOP
      END
C
C
      SUBROUTINE TO CALCULATE LINEAR LEAST SQUARES FIT
      SUBROUTINE LSQ1(X,Y,N,C,ERROR)
      PARAMETER ( MAX=100 )
       IMPLICIT DOUBLE PRECISION (A-H, O-Z)
      REAL*4 X(MAX), Y(MAX), YF(MAX), C(2), SUM, ERROR
      RN=FLOAT(N)
       SUMX=0.0
      SLMY=0.0
       SUPEXY=0.0
       SUMX2=0.0
      00 10 J=1,N
          DUBX = X(J)
                              I DOUBLE PRECISION X
          DUSY = Y(J)
          SURX . SURX + DUBX
          SUMY . BUMY + DUBY
          SUPCY = SUPCY + DUBX*DUBY
          SUPX2 = SUPX2 + DUSX**2
 10 CONTINUE
       DUBC2 = (RM*SURXY-SURXYSURY) / (RM*SURXZ-SURX*2)
       DUBC1 = (SUMY/RH) - (DUBC2*SUMX/RH)
       C(2) = DUBC2
       C(1) = DUSC1
       SUM = 0.
       DO 20 J=1,N
          YF(J)=C(2)*X(J)+C(1)
          SUM = SUM + (YF(J) - Y(J))*2
     CONTINUE
 20
       ERROR . SUM / FLOAT(N-2)
       RETURN
       END
```

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